

H.W 7

16-112

$$\vec{a}_A = \vec{a}_o + \vec{\alpha}_w \times \vec{r}_{A/I_0} - \omega_w^2 \vec{r}_{A/I_0}$$

$$= 0 + (-6\text{ rad/s}) \times (0.3 \cos 60^\circ i - 0.3 \sin 60^\circ j) \\ - (2)^2 (0.3 \cos 60^\circ i - 0.3 \sin 60^\circ j)$$

$$\vec{a}_A = -1.8 \cos 60^\circ i - 1.8 \sin 60^\circ i - 1.2 \cos 60^\circ i \\ + 1.2 \sin 60^\circ j$$

$$\Rightarrow \vec{a}_A = (-2.159 i + 0.1392 j) \text{ m/s}^2$$

To find \vec{a}_B ; \vec{w}_{AB} must be found first

Use the Ie

$$\frac{0.5}{\sin 60^\circ} = \frac{r_{A/I_C}}{\sin \alpha_s} \Rightarrow r_{A/I_C} = 0.4082 \text{ m}$$

$$w_{AB} = \frac{v_A}{r_{A/I_C}} = \frac{0.3(2)}{0.4082} = 1.47 \text{ rad/s}$$

$$\vec{a}_B = -a_B j = \vec{a}_A + \vec{\alpha}_{AB} \times \vec{r}_{B/I_A} - \omega_{AB}^2 \vec{r}_{B/I_A}$$

$$-a_B j = -2.159 i + 0.1392 j + (-\alpha_{AB} K) \times (0.5 \cos 45^\circ i + 0.5 \sin 45^\circ j) \\ - (1.47)^2 (0.5 \cos 45^\circ i + 0.5 \sin 45^\circ j)$$

$$-a_B j = -2.159 i + 0.1392 - 0.5 \alpha_{AB} \cos 45^\circ j + 0.5 \alpha_{AB} \sin 45^\circ i - 1.08 \cos 45^\circ j \\ - 1.08 \sin 45^\circ j$$

$$-a_B j = (-2.923 + 0.3536 \alpha_{AB}) i + (-0.6245 - 0.3536 \alpha_{AB}) j$$

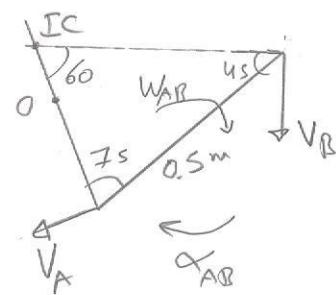
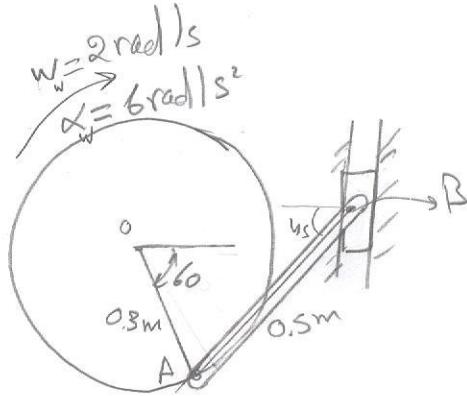
i-component

$$\Rightarrow \alpha_{AB} = \frac{-2.923}{0.3536} = 8.266 \text{ rad/s}^2$$

j-component

$$a_B = 0.6245 + 0.3536 \times 8.266 = 3.547 \text{ m/s}^2$$

$$\vec{a}_B = (-3.547 j) \text{ m/s}^2$$



16-130

Find \vec{w}_{AB} & $\vec{\alpha}_{AB}$

$$V_c = w_s r_s = 6 \times 0.175 = 1.05 \text{ m/s} \quad \checkmark$$

$$\alpha_c = \alpha_s r_s = 2 \times 0.175 = 0.35 \text{ rad/s}^2 \quad \checkmark$$

$$w_s = 6 \text{ rad/s}$$

$$\alpha_s = 2 \text{ rad/s}$$

$$r_{B/Ic} = \frac{0.15}{\sin 30} \sin(105) =$$

$$= 0.2898 \text{ m}$$

$$r_{c/Ic} = \frac{0.15}{\sin 30} \sin 45 = 0.2121 \text{ m}$$

$$w_{Bc} = \frac{V_c}{r_{c/Ic}} = \frac{1.05}{0.2121} = 4.95 \text{ rad/s} \quad \checkmark$$

$$V_B = w_{Bc}(r_{B/Ic}) = 4.95(0.2898) = 1.435 \text{ m/s}$$

$$w_{AB} = \frac{V_B}{r_{B/A}} = \frac{1.435}{0.2} = 7.173 \text{ rad/s} \quad \checkmark$$

$$\vec{a}_B = \vec{a}_c + (\vec{a}_{B/Ic})_t + (\vec{a}_{B/Ic})_n$$

Point B makes rotation about fixed axis (A)

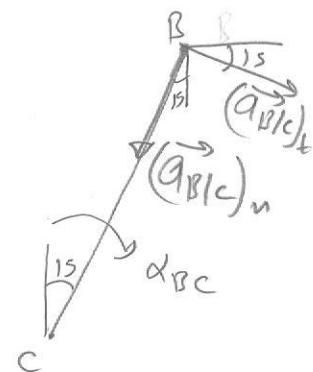
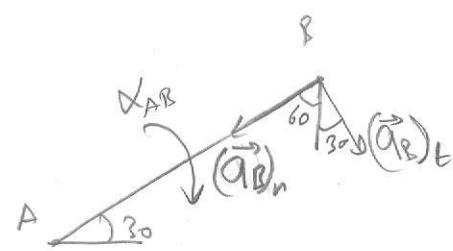
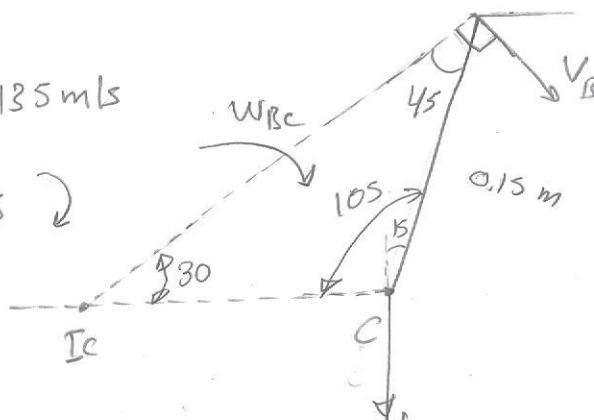
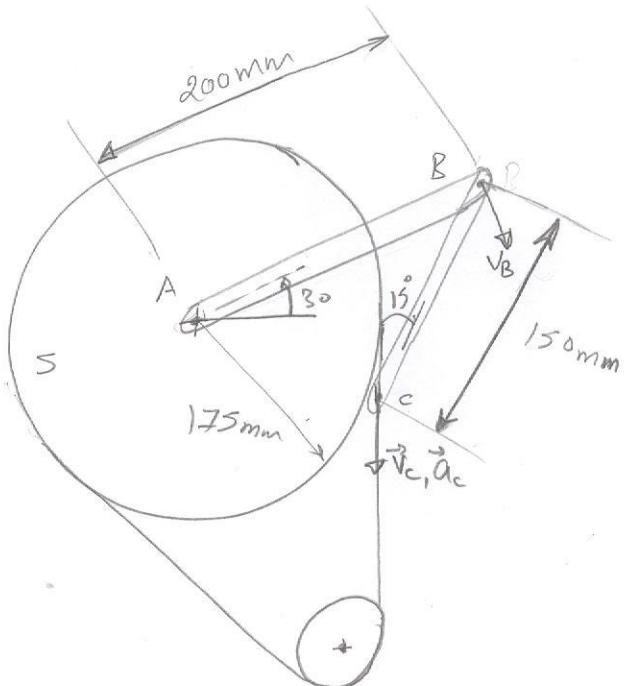
$$(\vec{a}_B)_t + (\vec{a}_B)_n = \vec{a}_c + (\vec{a}_{B/Ic})_t + (\vec{a}_{B/Ic})_n$$

$$0.2 \alpha_{AB} \downarrow_{30} + (7.173)^2(0.2) \downarrow_{60} = 1.05 \downarrow + \alpha_{Bc}(0.15) \downarrow_{45} + (4.95)^2(0.15) \downarrow_{15}$$

J-direction

$$0.2 \alpha_{AB} \cos 30 + (7.173)^2(0.2) \cos 60 = 1.05 + (0.15)(\alpha_{Bc}) \sin 15 + (4.95)^2(0.15) \cos 45$$

$$\Rightarrow \alpha_{Bc} = 4.46 + \alpha_{AB} + 32.07$$



i-direction

$$0.2 \alpha_{AB} \sin 30 - (7.173)^2 (0.2) \sin 60 = 0.15(4.461 \alpha_{AB} + 32.07) \cos 15 - (4.949)^2 (0.15) \sin 15$$

$$\Rightarrow \alpha_{AB} = -23.07 \text{ rad/s}^2 \rightarrow$$

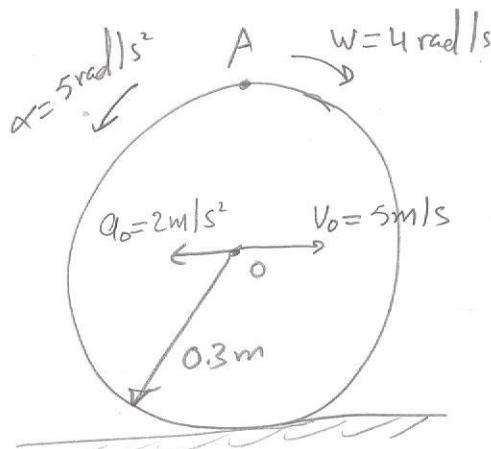
$$= 23.07 \text{ rad/s}^2 \uparrow$$

16-115

Find \vec{a}_A ?

$$V_0 = 5 \text{ m/s} \neq w r = 4(0.3) = 1.2 \text{ m/s}$$

→ slipping exists between the ground and the wheel



$$\vec{a}_A = \vec{a}_0 + (\vec{a}_{A/0})_t + (\vec{a}_{A/0})_n$$

$$\vec{a}_A = a_0 \leftarrow + (\vec{a}_{A/0})_t \leftarrow + (\vec{a}_{A/0})_n \downarrow$$

$$(\vec{a}_{A/0})_t = -2i - \alpha(r_{A/0})i - w^2(r_{A/0})j$$

$$\rightarrow \vec{a}_A = -2i - 5(0.3)i - 4^2(0.3)j \\ = (-3.5i - 4.8j) \text{ m/s}^2$$

$$|\vec{a}_A| = \sqrt{(3.5)^2 + (4.8)^2} = 5.941 \text{ m/s}^2$$

$$\theta = 126.1^\circ \quad \checkmark \theta$$

16-141

$$\vec{\omega}_{AB} = -\omega_{AB} \vec{k}$$

$$V_B = \omega_{AB} r_{AB} = 3(0.1) = 0.3 \text{ m/s}$$

$$\vec{v}_B = -0.3 \vec{j}$$

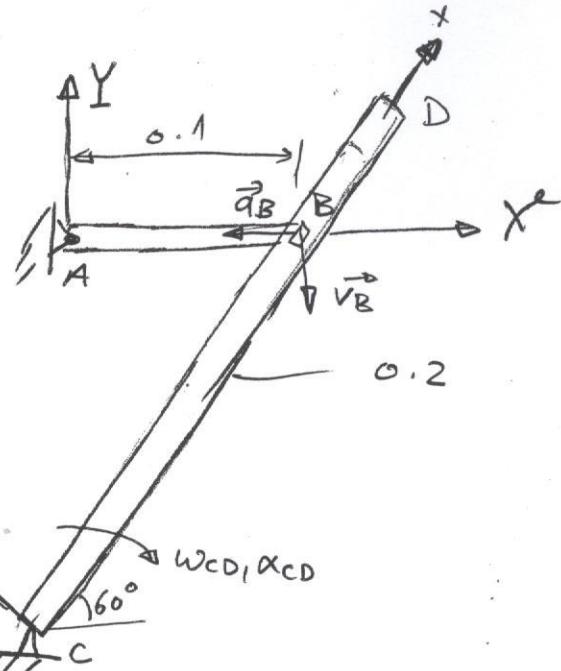
$$\vec{a}_B = \vec{a}_A + \vec{\alpha}_{AB} \times \vec{r}_{B/A} - \omega_{AB}^2 \vec{r}_{B/A}$$

$$\omega_{AB} = \text{const.} \rightarrow \alpha_{AB} = 0$$

$$\vec{r}_{B/A} = 0.1 \vec{i}$$

$$\vec{a}_B = 0 + 0 - \omega_{AB}^2 \vec{r}_{B/A}$$

$$\vec{a}_B = -0.9 \vec{i}$$



$$\vec{v}_B = -0.3 \vec{j} = -0.3(\cos 30 \vec{i} + \sin 30 \vec{j})$$

$$\vec{a}_B = -0.9 \vec{i} = 0.9(-\cos 60 \vec{i} + \sin 60 \vec{j})$$

Link CD

$$\vec{v}_B = \vec{v}_C + \vec{\omega} \times \vec{r}_{B/C} + (\vec{v}_{B/C})_{xy}$$

$$\vec{\omega} = -\omega_{CD} \vec{k}; \quad \vec{r}_{B/C} = 0.2 \vec{c} \quad (\vec{v}_{B/C})_{xy} = -(v_{B/C})_{xy} \vec{c}$$

$$-0.3(\cos 30 \vec{i} + \sin 30 \vec{j}) = 0 - \omega_{CD} \vec{k} \times (0.2) \vec{c} - (v_{B/C})_{xy} \vec{c}$$
$$= -0.2 \omega_{CD} \vec{j} - (v_{B/C})_{xy} \vec{i}$$

$$i: (v_{B/C})_{xy} = 0.26 \text{ m/s}$$

$$j: \omega_{CD} = 0.75 \text{ rad/s}$$

$$\vec{a}_B = \vec{a}_C + \vec{\omega} \times \vec{r}_{B/C} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{B/C}) + 2 \vec{\omega} \times (\vec{v}_{B/C})_{xy} + (\vec{a}_{B/C})_{xy} \quad (*)$$

$$\vec{a}_C = 0; \quad \vec{\omega} = -0.75 \vec{k} \quad \vec{\omega} = -\alpha_{CD} \vec{k}$$

$$(\vec{v}_{B/C})_{xy} = -0.26 \vec{c} \quad (\vec{a}_{B/C})_{xy} = (\alpha_{B/C})_{xy} \vec{c}$$

$$\vec{R} \times \vec{v}_{B/C} = -\alpha_{CD} \vec{k} \times 0.2 \vec{i} = -0.2 \alpha_{CD} \vec{j}$$

$$\vec{J} \times (\vec{R} \times \vec{v}_{B/C}) = -0.75 \vec{k} \times (-0.75 \vec{k} \times 0.2 \vec{i}) = -0.1125 \vec{i}$$

$$z \vec{J} \times (\vec{v}_{B/C})_{xy} = z(-0.75) \vec{k} \times (-0.26) \vec{i} = 0.39 \vec{j}$$

Substituting into *)

$$-0.9 \cos 60 \vec{i} + 0.9 \sin 60 \vec{j} = -0.2 \alpha_{CD} \vec{j} - 0.1125 \vec{i} + 0.39 \vec{j} + (a_{B/C})_{xy} \vec{i}$$

$$j: 0.9 \sin 60 = 0.39 - 0.2 \alpha_{CD}$$

$$\hookrightarrow \alpha_{CD} = -1.947 \text{ rad/s}$$

$$i: -0.9 \cos 60 = -0.1125 + (a_{B/C})_{xy}$$

$$\hookrightarrow (a_{B/C})_{xy} = -0.3375 \text{ m/s}^2$$

16-147

$$\vec{v}_B = \vec{\omega}_{AB} \times \vec{r}_{B/A}$$

$$\vec{\omega}_{AB} = 2\vec{k}$$

$$\vec{r}_{B/A} = 5\cos 30 \vec{i} + 5\sin 30 \vec{j}$$

$$\vec{v}_B = 10\vec{k} \times (\omega_{30}\vec{i} + \sin 30 \vec{j})$$

$$= 10(\cos 30 \vec{j} - \sin 30 \vec{i})$$

$$= -5\vec{i} + 8.66\vec{j}$$

$$\omega_{AB} = \text{const.}$$

$$\hookrightarrow \alpha_{AB} = 0 \quad \alpha_A = 0$$

$$\vec{a}_B = \vec{a}_A + \vec{\alpha}_{AB} \times \vec{r}_{B/A} - \omega_{AB}^2 \vec{r}_{B/A}$$

$$= 0 + 0 - (2)^2(5\cos 30 \vec{i} + 5\sin 30 \vec{j})$$

$$\vec{a}_B = -17.32\vec{i} - 10\vec{j}$$

x, y are parallel to X, Y *at the instant!*

$$\vec{v}_B = -5\vec{i} + 8.66\vec{j} \quad \vec{a}_B = -17.32\vec{i} - 10\vec{j}$$

x, y is attached to the disk $\rightarrow (\vec{v}_{C/B})_{xy} = (\vec{a}_{C/B})_{xy} = 0$

$$\vec{r}_{C/B} = (2 - 0.5)\vec{k} = 1.5\vec{k} \quad \vec{r}_{C/B} = -\vec{j}$$

$$\vec{v}_C = \vec{v}_B + \vec{\omega} \times \vec{r}_{C/B} + (\vec{v}_{C/B})_{xy}$$

$$= -5\vec{i} + 8.66\vec{j} + 1.5\vec{k} \times (-\vec{j}) + 0$$

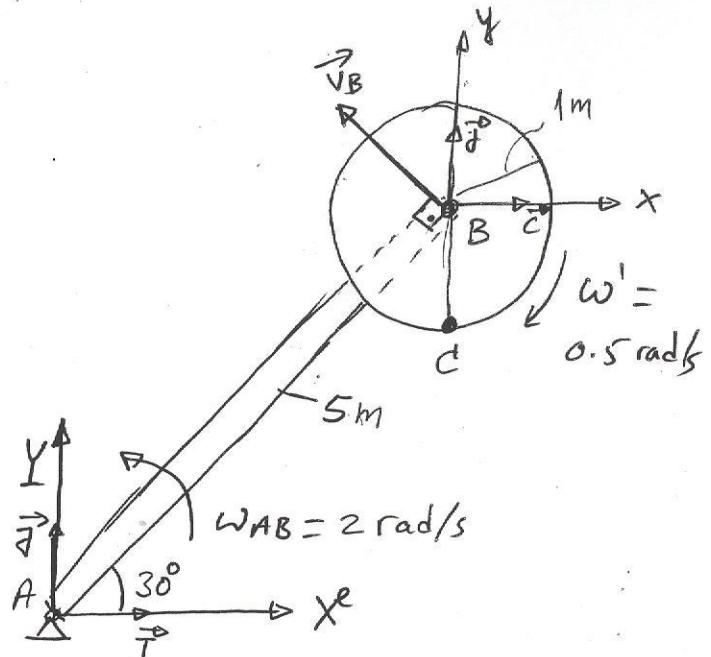
$$\vec{v}_C = -3.5\vec{i} + 8.66\vec{j}$$

$$\vec{a}_C = \vec{a}_B + \vec{\omega} \times \vec{r}_{C/B} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{C/B}) + 2\vec{\omega} \times (\vec{v}_{C/B})_{xy} + (\vec{a}_{C/B})_{xy}$$

$$= -17.32\vec{i} - 10\vec{j} + 0 + 1.5\vec{k} \times [1.5\vec{k} \times (-\vec{j})] + 0 + 0$$

$$= -17.32\vec{i} - 10\vec{j} + 1.5\vec{i} + 1.5^2\vec{j}$$

$$\vec{a}_C = -17.32\vec{i} - 7.75\vec{j}$$



since C is attached to the rigid disk

$$\vec{\omega} = \text{const} \\ \vec{\omega} = 0$$