

22-10

given:

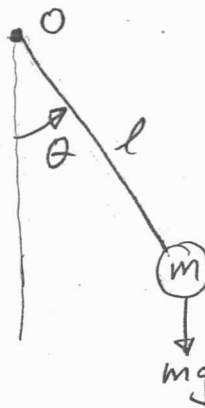
$$l = 0.4 \text{ m}$$

$$v_0 = -0.2 \text{ m/s}$$

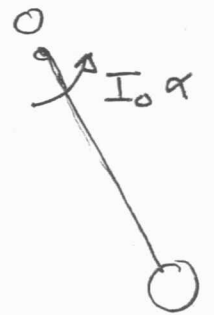
$$v = \omega r$$

$$\rightarrow \omega_0 = -0.5 \text{ rad/s}$$

$$\theta_0 = 0.3 \text{ rad} \triangleq 17.2^\circ$$



FBD



KD

$$\hookrightarrow \sum M_O = I_O \ddot{\theta} \quad I_O = ml^2$$

$$-mgl \sin \theta = ml^2 \ddot{\theta}$$

$$\text{or} \quad \ddot{\theta} + \frac{g}{l} \sin \theta = 0$$

Assume: small oscillations $\rightarrow \sin \theta \approx \theta$

$$\ddot{\theta} + \omega_n^2 \theta = 0$$

$$\omega_n = \sqrt{g/l} = 4.95 \text{ rad/s}$$

Solution:

$$\theta(t) = A \cos \omega_n t + B \sin \omega_n t$$

$$\dot{\theta}(t) = -A \omega_n \sin \omega_n t + B \omega_n \cos \omega_n t$$

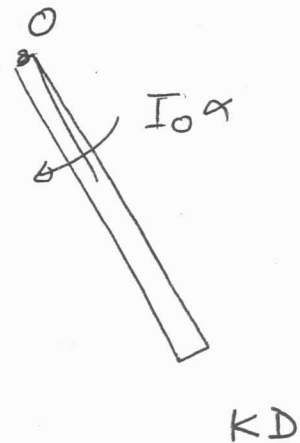
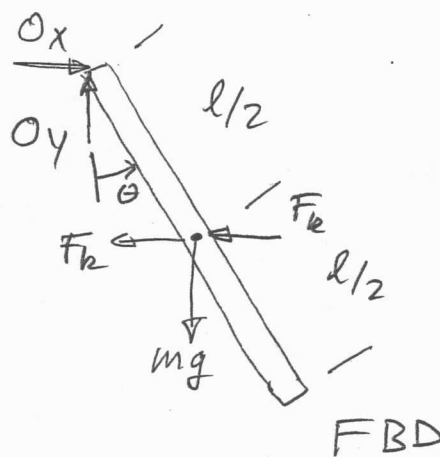
initial conditions:

$$\theta(0) = 0.3 = A \cos 0 + B \sin 0 \Rightarrow \boxed{A = 0.3}$$

$$\dot{\theta}(0) = \omega_0 = -0.5 = B \omega_n \Rightarrow B = \frac{-0.5}{\omega_n} = -0.1$$

$$\hookrightarrow \theta(t) = 0.3 \cos 4.95t - 0.1 \sin 4.95t$$

22-12



$$\sum M_o = I_o \alpha$$

$$\alpha = \ddot{\theta} \quad I_o = \frac{ml^2}{3}$$

$$-mg\left(\frac{l}{2}\right) \sin \theta - 2F_k\left(\frac{l}{2}\right) \cos \theta = \frac{ml^2}{3} \ddot{\theta}$$

$$F_k = k \Delta s = k\left(\frac{l}{2}\right) \sin \theta$$

small oscillations : $\sin \theta \approx \theta$ $\cos \theta \approx 1$

$$\hookrightarrow m \frac{l^2}{3} \ddot{\theta} + \left[mg \frac{l}{2} + 2k \frac{l}{2} \frac{l}{2} \right] \theta = 0$$

or

$$\ddot{\theta} + \frac{3(mg + kl)}{2ml} \theta = 0$$

$$\omega_n = \sqrt{\frac{3(mg + kl)}{2ml}} = 5.688 \text{ rad/s}$$

$$\hookrightarrow f_n = \frac{\omega_n}{2\pi} = 0.905 \text{ Hz}$$

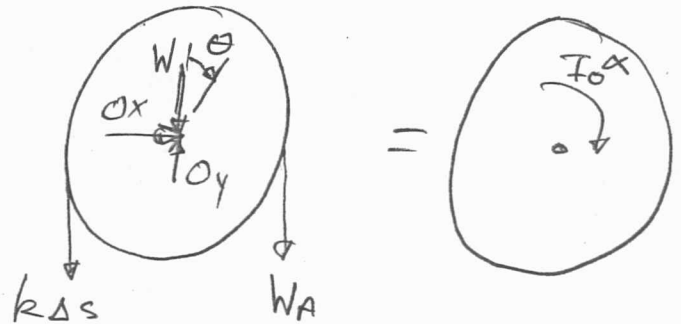
22-20

$$r = 0.75 \text{ m}$$

$$m_D = 1529.052 \text{ kg}$$

$$m_A = 305.81 \text{ kg}$$

$$k = 80 \text{ kN/m}$$



Assume:

block is a particle $\rightarrow I_{AG} = 0$

$$I_O = \frac{1}{2} m_D r^2 + m_A r^2 = \left(\frac{1}{2} m_D + m_A \right) r^2 = 602.064 \text{ kg m}^2$$

$$\Delta s = r \theta$$

From static equilibrium position

$$\uparrow \sum M_O = I_O \alpha$$

$$I_O \ddot{\theta} + k r^2 \theta = 0$$

$$\ddot{\theta} + \omega_n^2 \theta = 0$$

$$\omega_n = \sqrt{\frac{k r^2}{I_O}} = \sqrt{\frac{80000 (0.75)^2}{602.064}}$$

$$\omega_n = 8.645 \text{ rad/s}$$

$$\tau_n = \frac{2\pi}{\omega_n} = 0.727 \text{ s}$$

22-341

$$l = 0.75 \text{ m}$$

$$a = 0.5 \text{ m}$$

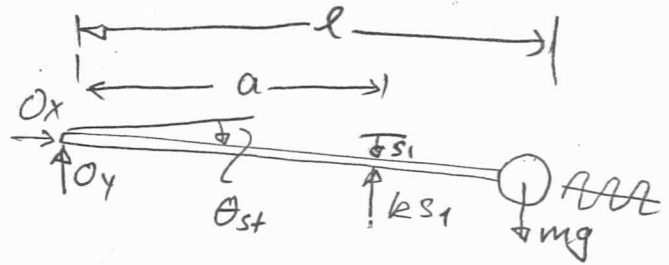
Static equilibrium θ_{st}

$$\sum M_O = 0$$

$$k s_1 (a) - mgl = 0$$

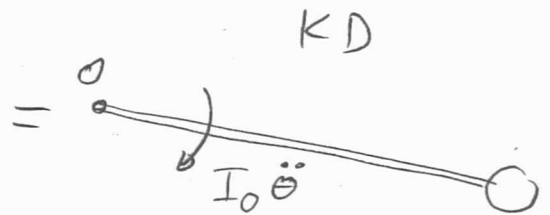
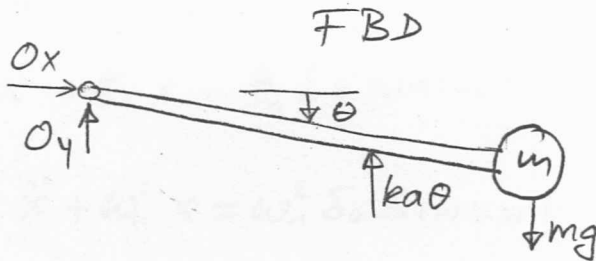
$$k \theta_{st} a^2 - mgl = 0 \Rightarrow \boxed{\theta_{st} = \frac{mgl}{ka}}$$

$$\theta_{st} = 0.196 \text{ rad} \equiv 11.24^\circ$$



$$s_1 = \theta_{st} \cdot a$$

Dynamic equilibrium:



Assume:

small oscillation

vibration about the static equilibrium position

$$\sum M_O = I_O \ddot{\theta} \quad I_O = ml^2 = 20(0.75)^2 = 11.25 \text{ kg m}^2$$

$$-ka^2\theta = ml^2 \ddot{\theta}$$

$$\text{or } \ddot{\theta} + \frac{ka^2}{ml^2} \theta = 0$$

$$\ddot{\theta} + \omega_n^2 \theta = 0$$

$$\omega_n = \sqrt{\frac{ka^2}{ml^2}} = \sqrt{\frac{150(0.5)^2}{2(0.75)^2}} = 5.7735 \text{ rad/s}$$

$$f_n = \frac{\omega_n}{2\pi} = 0.92 \text{ Hz}$$

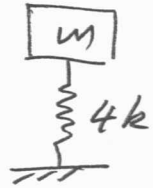
22-49

given:

$$m = 18 \text{ kg} \quad k = 130 \text{ N/m}$$

$$y(t) = \delta_0 \sin \omega_0 t \quad \delta_0 = 0.17 \text{ m}$$

$$f_0 = 7 \text{ Hz} \rightarrow \omega_0 = 2\pi(7) = 43.982 \text{ rad/s}$$



Determine the vertical displacement of the mass

Equation of motion:

$$m \ddot{x} + kx = ky$$

$$\ddot{x} + \frac{k}{m}x = \frac{k}{m}\delta_0 \sin \omega_0 t$$

or

$$\ddot{x} + \omega_n^2 x = \omega_n^2 \delta_0 \sin \omega_0 t$$

$$\omega_n = \sqrt{\frac{4k}{m}} = 5.3748 \text{ rad/s}$$

$$x(t) = X_0 \sin \omega_0 t$$

$$\text{where } X_0 = \frac{\delta_0}{1 - \left(\frac{\omega_0}{\omega_n}\right)^2} = \frac{0.17}{1 - \left(\frac{43.982}{5.3748}\right)^2}$$

$$X_0 = 2.57726 \text{ mm}$$