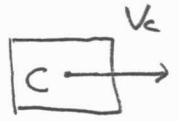
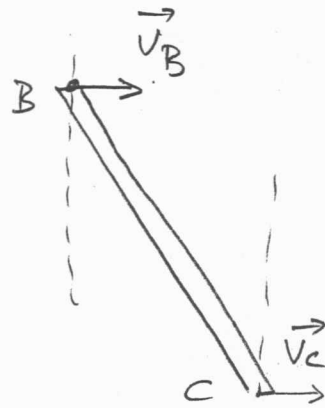
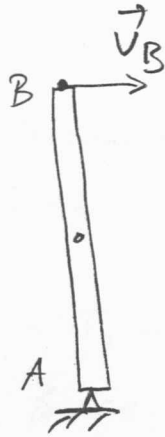


18.7]



Block C:

$$T_C = \frac{1}{2} m_C v_C^2 = \frac{1}{2} (4) (1)^2 = 2 \text{ J}$$

link CB

$$r_{B/C} = r_{C/C} \rightarrow \infty \quad \text{moves translational! } v = 1 \text{ m/s}$$

$$T_{CB} = \frac{1}{2} m v^2 = \frac{1}{2} \frac{200}{9.81} (1)^2 = 10.194 \text{ J}$$

link AB

$$v_B = 1 \text{ m/s} = r_{AB} \omega_{AB} = 1 \omega_{AB} \Rightarrow \omega_{AB} = 1 \text{ rad/s}$$

$$T_{AB} = \frac{1}{2} I_A \omega^2 = \frac{1}{2} \frac{1}{3} m_B (1)^2 (1)^2$$

$$= \frac{1}{6} \frac{100}{9.81} = 1.6989$$

$$T = T_C + T_{CB} + T_{AB}$$

$$= 13.893 \text{ J}$$

18-91

starting from rest

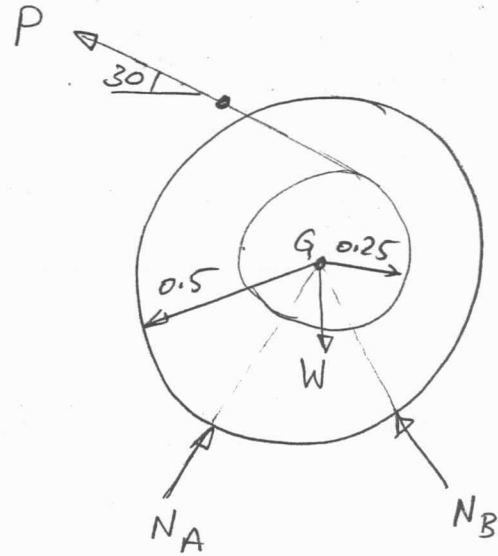
$$\hookrightarrow \omega_1 = 0$$

$$\sum U_{1-2} = T_2 - T_1$$

- only force P does work

displacement of P

$$s_P = 2(2\pi)(0.25) = \pi \text{ m}$$



- pure rotation about a fixed axis

$$I_G = m k_G^2 = (175)(0.42)^2 = 30.87 \text{ kg m}^2$$

$$\sum U_{1-2} = T_2 - T_1$$

$$P s_P = \frac{1}{2} I_G \omega^2 - 0$$

$$20(\pi) = \frac{1}{2} (30.87) \omega^2$$

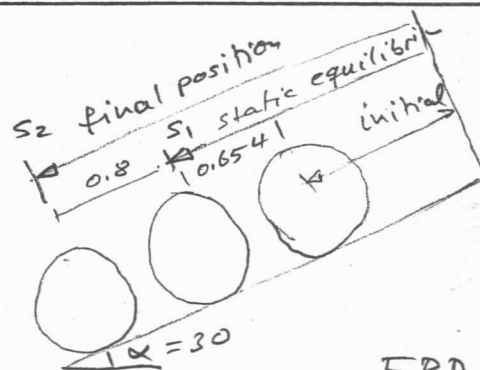
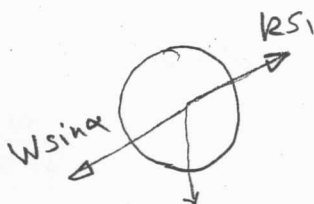
$$\hookrightarrow \omega = 2.0176 \text{ rad/s}$$

18-22

static equilibrium

$$ks_1 = mg \sin \alpha$$

$$s_1 = \frac{mg \sin \alpha}{k} = 0.654 \text{ m}$$



$$I_G = \frac{1}{2} m r^2 = \frac{1}{2} (20) (0.2)^2 = 0.4 \text{ kg m}^2$$

$s = r \theta$ without slipping

$$\Rightarrow \theta = \frac{s}{r} = \frac{0.8}{0.2} = 4 \text{ rad}$$

$$v_G = \omega r_G = 0.2 \omega$$

$$T_1 + \sum U_{1-2} = T_2$$

$$0 + mg \sin \alpha (0.8) - \frac{k}{2} (s_2^2 - s_1^2) + M \theta = \frac{1}{2} m v_G^2 + \frac{1}{2} I_G \omega^2$$

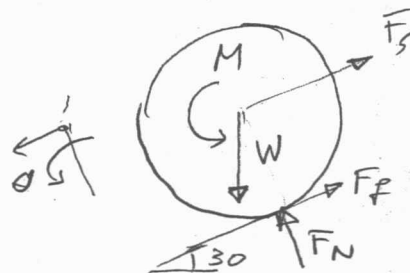
$$20(9.81) \sin 30 (0.8) - \frac{150}{2} [(0.8 + 0.654)^2 - (0.654)^2] + 30(4)$$

$$= \frac{1}{2} (I_G + m r_G^2) \omega^2$$

$$r_G = 0.2 \text{ m}$$

$$\Rightarrow \omega = 10.96 \text{ rad/s}$$

FBD



$$\underline{18-36}$$

$$T_1 + V_1 = T_2 + V_2$$

$$0 = \frac{1}{2} m_c v_c^2 + 4 \left[\frac{1}{2} m_w v_w^2 + \frac{1}{2} I_w \omega_w^2 \right] - [m_c + 4m_w] g h$$

$$m_c = \frac{550}{9.81} = 56.07 \text{ kg}$$

$$m_w = \frac{25}{9.81} = 2.548$$

$$V_c = V_w$$

$$V_w = r_w \omega_w$$

$$\omega_w = \frac{V_w}{0.15} = \frac{V_c}{0.15}$$

$$h = 30 \sin 30 = 15$$

$$0 = \left[\frac{1}{2}(56.07) + 4\left(\frac{1}{2}(2.548) + \frac{1}{2}(2.548)(0.09)^2\right) \right] \text{ k}^2 - [56.07 + 4(2.548)](9.81)(15)$$

$$\hookrightarrow V_c = 17.14 \text{ m/s}$$

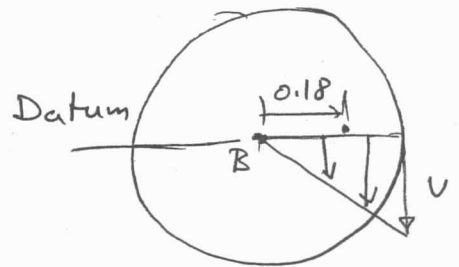
18-561

$$V_c = 0.18 \omega_B \Rightarrow \omega_B = \frac{V_c}{0.18}$$

$$T_1 + V_1 = T_2 + V_2$$

$$0 = W_c(1.5) = \frac{1}{2} m_c v_c^2 + \frac{1}{2} I_B \omega_B^2 - W_c(3)$$

$$-10(9.81)(1.5) = \frac{1}{2}(10)(9.81)V_c^2 + \frac{1}{2}(15)(0.18)^2 \frac{V_c^2}{(0.18)^2} - 10(9.81)(3)$$



$$\hookrightarrow V_c = 1.613 \text{ m/s}$$